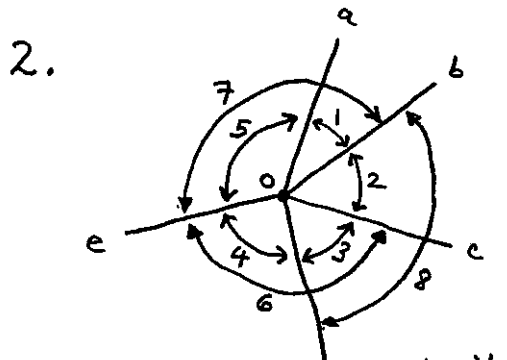


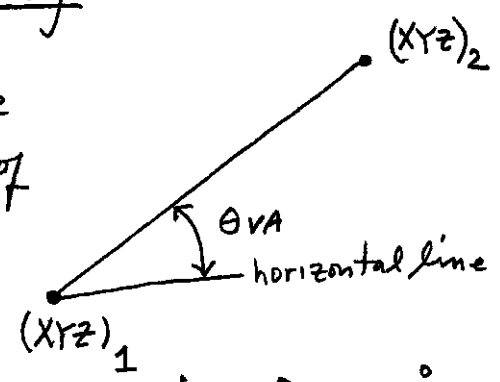
1. A weight matrix is given as $W = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 4 \end{bmatrix}$
 $\sigma_2 = 0.566$, what is σ_4 ?



2. For the angle figure in the sketch, we know that angle $\angle aoc$ is fixed at exactly 90° . With the given angle observations we wish to adjust the figure. What are n , n_0 , and r ?

Write the required number of condition equations for the observation only method.

3. Write a condition equation for the observed vertical angle, θ_{VA} , in terms of the point coordinates $x_1, y_1, z_1, x_2, y_2, z_2$.



Assume that we adjust a 3D network by indirect observations, with the point coordinates as unknowns. With $\theta_{VA} = 19.47^\circ$, and with approximations $(x, y, z)_1 = (10, 10, 10)$ and $(x, y, z)_2 = (20, 20, 15)$, evaluate $\frac{\partial F}{\partial z_1}$ and $f = -F(l, x^0)$. Give numerical values.

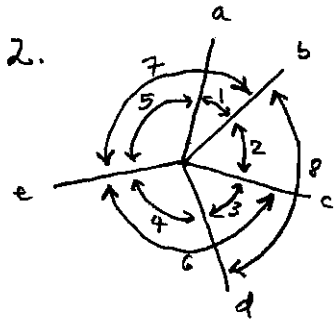
4. A surface is defined by the model $z = a_0 + a_1x + a_2y + a_3xy$. If 10 points are observed on the surface in all 3 coordinates, and you wish to fit the surface by general least squares, what are n , n_0 , and r ?

Useful facts: $\frac{d}{dx} \sin^{-1} u = \frac{1}{\sqrt{1-u^2}} \frac{du}{dx}$, $\frac{d}{dx} \cos^{-1} u = \frac{-1}{\sqrt{1-u^2}} \frac{du}{dx}$,
 $\frac{d}{dx} \tan^{-1} u = \frac{1}{1+u^2} \frac{du}{dx}$

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1. $W = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 4 \end{bmatrix}$ $\sigma_2 = 0.566$, $\sigma_2^2 = 0.32$, $w_2 = \sigma_0^2 / \sigma_2^2$, $\sigma_0^2 = \sigma_2^2 w_2$
 $\sigma_0^2 = 0.32 \times 2 = 0.64$, $w_4 = 4 = \sigma_0^2 / \sigma_4^2$

$\sigma_4^2 = \sigma_0^2 / 4 = \frac{0.64}{4} = 0.16$, $\sigma_4 = \underline{\underline{0.4}}$



$n = 8$
 $n_0 = 3$
 $r = 5$

for observations only need $c = r = 5$ condition equations

$\hat{l}_1 + \hat{l}_2 + \hat{l}_3 + \hat{l}_4 + \hat{l}_5 = 360^\circ$

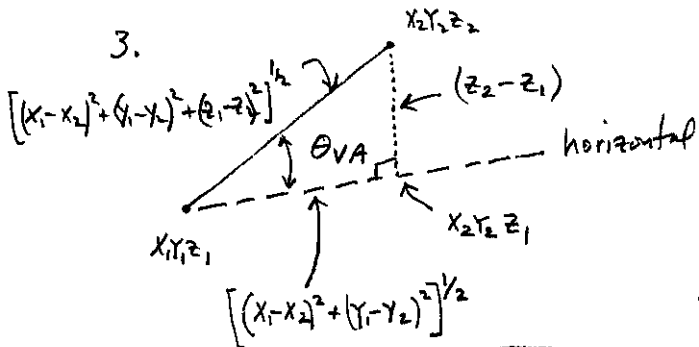
$\hat{l}_1 + \hat{l}_2 = 90^\circ$

$\hat{l}_1 + \hat{l}_5 = \hat{l}_7$

$\hat{l}_3 + \hat{l}_4 = \hat{l}_6$

$\hat{l}_2 + \hat{l}_3 = \hat{l}_8$

3.



$\theta_{VA} = \tan^{-1} \frac{(z_2 - z_1)}{[(x_2 - x_1)^2 + (y_2 - y_1)^2]^{1/2}}$

(a) $F_{\theta_{VA}} = \theta_{VA} - \tan^{-1} \frac{(z_2 - z_1)}{[(x_2 - x_1)^2 + (y_2 - y_1)^2]^{1/2}} = 0$

OR

(b) $F_{\theta_{VA}} = \theta_{VA} - \sin^{-1} \frac{(z_2 - z_1)}{[(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2]^{1/2}} = 0$

OR

(c) $F_{\theta_{VA}} = \theta_{VA} - \cos^{-1} \frac{[(x_2 - x_1)^2 + (y_2 - y_1)^2]^{1/2}}{[(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2]^{1/2}} = 0$

$dx = x_2 - x_1$ $dx_y = [dx^2 + dy^2]^{1/2}$
 $dy = y_2 - y_1$ $dx_{yz} = [dx^2 + dy^2 + dz^2]^{1/2}$
 $dz = z_2 - z_1$

(a) $\frac{\partial F}{\partial z_1} = \frac{-1}{1+u^2} \cdot \frac{du}{dz_1} = - \frac{1}{1 + \frac{dz^2}{dx_y^2}} \cdot \frac{-1}{dx_y} = \frac{1}{dx_y + \frac{dz^2}{dx_y}} = \frac{1}{14.142 + \frac{25}{14.142}} = \underline{.0628}$

$f = -F(l, x^0) = -(19.47 - \tan^{-1}(\frac{5}{14.142})) = \underline{.0014^\circ} = \underline{2.4 \times 10^{-5} \text{ Rad}}$

(b) $\frac{\partial F}{\partial z_1} = - \frac{1}{\sqrt{1-u^2}} \cdot \frac{du}{dz_1} = \frac{1}{\sqrt{1 - \frac{dz^2}{dx_{yz}^2}}} \cdot \frac{dx_{yz} \cdot (-1) - dz \cdot \frac{1}{2} (dx_{yz}^2)^{-1/2} \cdot 2 dz \cdot (-1)}{dx_{yz}^2}$
 $= \frac{1}{\sqrt{1 - \frac{dz^2}{dx_{yz}^2}}} \cdot \frac{dx_{yz} - dz^2}{dx_{yz}^3} = \frac{1}{\sqrt{1 - \frac{25}{225}}} \cdot \frac{225 - 25}{(15)^3} = \underline{.0628}$

$f = -F(l, x^0) = -(19.47 - \sin^{-1}(\frac{5}{15})) = \underline{.0012^\circ} = \underline{2.1 \times 10^{-5} \text{ Rad}}$

$dx = 10$ $dx_y = 14.142$
 $dy = 10$ $dx_{yz} = 15$
 $dz = 5$

$$(c) \frac{\partial F}{\partial z_1} = - \frac{-1}{\sqrt{1-y^2}} \frac{dy}{dz_1} = \frac{1}{\sqrt{1-\frac{d^2_{xyz}}{d^2_{xyz}}}} \cdot \frac{d_{xyz} \cdot 0 + d_{xyz} \cdot \frac{1}{2} (D^2_{xyz})^{-1/2} \cdot 2 \cdot dz_1 \cdot (-1)}{d^2_{xyz}}$$

$$\frac{1}{\sqrt{1-\frac{d^2_{xy}}{d^2_{xyz}}}} \frac{d_{xy} \cdot dz}{d^3_{xyz}} = \frac{1}{\sqrt{1-\frac{200}{225}}} \cdot \frac{14.142 \cdot 5}{(15)^3} = \underline{0.0628}$$

$$f = -F(\theta, x^0) = -\left(19.47 - \cos^{-1}\left(\frac{14.142}{15}\right)\right) = \underline{.0028^\circ} = \underline{4.8 \times 10^{-5} \text{ Rad}}$$

(note: with full precision f for all 3 expressions is .0012)

4. $z = a_0 + a_1x + a_2y + a_3xy$, 10 points observed in x, y, z

general LS: $n = 10 \times 3 = 30 \leftarrow n$

$n_0 = 4 + 2 \times 10 = 24 \leftarrow n_0$

$r = 6 \leftarrow r$

$\mu = 4 \quad a_0, a_1, a_2, a_3$

$C = r + \mu = 10$; one equation per point.