

CE 597 (029) Adj. of Geospatial Obs. HW2 Solution
10 Oct. 2008

1. Observations only: need $c=r=5$ condition equations

$$\begin{aligned} n &= 10 \\ n_0 &= 5 \\ r &= 5 \end{aligned}$$

$$1. \hat{l}_1 + \hat{l}_2 + \hat{l}_8 = 180$$

$$2. \hat{l}_2 + \hat{l}_3 + \hat{l}_4 = 360$$

$$3. \hat{l}_9 - \hat{l}_8 + \hat{l}_3 + \hat{l}_5 = 180$$

$$4. \hat{l}_{10} - (\hat{l}_9 - \hat{l}_8) + \hat{l}_6 + \hat{l}_7 = 180$$

$$\hat{l}_{10} - \hat{l}_9 + \hat{l}_8 + \hat{l}_6 + \hat{l}_7 = 180$$

$$5. \hat{l}_8 + \hat{l}_{10} = 180$$

$$l_1 + v_1 + l_2 + v_2 + l_8 + v_8 = 180$$

$$l_2 + v_2 + l_3 + v_3 + l_4 + v_4 = 360$$

$$l_9 + v_9 - l_8 - v_8 + l_3 + v_3 + l_5 + v_5 = 180$$

$$l_{10} + v_{10} - l_9 - v_9 + l_8 + v_8 + l_6 + v_6 + l_7 + v_7 = 180$$

$$l_8 + v_8 + l_{10} + v_{10} = 180$$

$$v_1 + v_2 + v_8 = 180 - (l_1 + l_2 + l_8)$$

$$v_2 + v_3 + v_4 = 360 - (l_2 + l_3 + l_4)$$

$$v_9 - v_8 + v_3 + v_5 = 180 - (l_9 - l_8 + l_3 + l_5)$$

$$v_{10} - v_9 + v_8 + v_6 + v_7 = 180 - (l_{10} - l_9 + l_8 + l_6 + l_7)$$

$$v_8 + v_{10} = 180 - (l_8 + l_{10})$$

$$\begin{bmatrix} 1 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 0 & 0 & -1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 1 & 1 & -1 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \\ v_5 \\ v_6 \\ v_7 \\ v_8 \\ v_9 \\ v_{10} \end{bmatrix} = \begin{bmatrix} 180 \\ 360 \\ 180 \\ 180 \\ 180 \end{bmatrix} - \begin{bmatrix} 1 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 0 & 0 & -1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 1 & 1 & -1 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} l_1 \\ l_2 \\ l_3 \\ l_4 \\ l_5 \\ l_6 \\ l_7 \\ l_8 \\ l_9 \\ l_{10} \end{bmatrix}$$

$A \cdot V = d - A \cdot l$

$$\begin{aligned} Av &= d - Al \\ Av &= f \end{aligned}$$

choose $\sigma_0 = 2$, $\sigma_0^2 = 4$, $w_i = \sigma_0^2 / \sigma_i^2$
Solution from Matlab:

$$K = W e f$$

$$V = Q A^T K$$

$$W e = (A Q A^T)^{-1}, \quad Q = W^{-1}, \quad f = d - A l$$

(from Matlab)

$$K = \begin{bmatrix} 0.475 \\ -1.55 \\ 0.175 \\ 0.725 \\ 0.125 \end{bmatrix}$$

$$V = \begin{bmatrix} .119 \\ -.269 \\ -.344 \\ -.388 \\ .044 \end{bmatrix}, \quad \begin{bmatrix} .725 \\ .725 \\ 1.15 \\ -.55 \\ .85 \end{bmatrix}$$

$$\hat{l} = \begin{bmatrix} 61.119 \\ 57.731 \\ 61.656 \\ 240.613 \\ 59.044 \end{bmatrix}, \quad \begin{bmatrix} 48.725 \\ 71.725 \\ 61.15 \\ 120.45 \\ 118.85 \end{bmatrix}$$

2. $Z = a_0 + a_1x + a_2y + a_3(x^2 + y^2)$ (paraboloid of revolution)

indirect observations z : obs, x, y : constant

$n = 6$ for matrix solution, put in form $V + Ba = f$:

$n_0 = 4$ $z_i + v_i = a_0 + a_1x_i + a_2y_i + a_3(x_i^2 + y_i^2)$

$r = 2$ $v_i - a_0 - a_1x_i - a_2y_i - a_3(x_i^2 + y_i^2) = -z_i$ ←

$$B = \begin{bmatrix} -1 & -5 & -5 & -50 \\ -1 & 5 & -6 & -61 \\ -1 & 4 & 3 & -25 \\ -1 & -4 & 2 & -20 \\ -1 & 2 & -2 & -8 \\ -1 & -1 & 0 & -1 \end{bmatrix}, f = \begin{bmatrix} -4.28 \\ -5.61 \\ -5.47 \\ -4.23 \\ -3.42 \\ -3.23 \end{bmatrix}, c = n = 6, u = n_0 = 4$$

$\sigma_0 = 0.02$, for $\sigma_i = .02, w_i = 1$, for $\sigma_i = .01, w_i = \frac{(.02)^2}{(.01)^2} = \frac{.0004}{.0001} = 4$

$W = \begin{bmatrix} 1 & & & \\ & 4 & & \\ & & 4 & \\ & & & 4 & \\ 0 & & & & 4 & \\ & & & & & 4 \end{bmatrix}$ problem is linear so no iterations are required.

$$\Delta = (B^T W B)^{-1} B^T W f, v = f - B \Delta$$

$$\Delta = \begin{bmatrix} a_0 \\ a_1 \\ a_2 \\ a_3 \end{bmatrix} = \begin{bmatrix} 3.2447 \\ -.0970 \\ -.1944 \\ .0498 \end{bmatrix}, v = \begin{bmatrix} -.00008 \\ -.00641 \\ -.00820 \\ .01237 \\ .02859 \\ -.03247 \end{bmatrix}, \hat{z} = \begin{bmatrix} 4.28 \\ 5.60 \\ 5.46 \\ 4.24 \\ 3.45 \\ 3.20 \end{bmatrix}$$

3. Trilateration, indirect observations

non-linear problem!
must iterate solution

$n = 5$
 $n_0 = 2$ x, y
 $r = 3$
 $c = n = 5$
 $u = n_0 = 2$

$$d_i = [(x - x_i)^2 + (y - y_i)^2]^{1/2}$$

$$F_i = d_i - [(x - x_i)^2 + (y - y_i)^2]^{1/2} = 0$$

$B = \partial F / \partial x$, $f = -F_i$, see graphic for initial Approx $\begin{pmatrix} x_0 \\ y_0 \end{pmatrix} = \begin{pmatrix} 410.5 \\ 462.4 \end{pmatrix}$

$$\frac{\partial F_i}{\partial x} = -\frac{(x - x_i)}{D_i}$$

$$\frac{\partial F_i}{\partial y} = -\frac{(y - y_i)}{D_i}$$

$$D_i = [(x_0 - x_i)^2 + (y_0 - y_i)^2]^{1/2}$$

$$B = \begin{bmatrix} .42589 & .70477 \\ .99905 & -.043544 \\ .19971 & -.97986 \\ -.94523 & -.3624 \\ -.77559 & .63124 \end{bmatrix}, f = \begin{bmatrix} -2.4229 \\ -.4799 \\ 2.3474 \\ 1.1803 \\ -1.0864 \end{bmatrix}$$

first iter. first iter.

$$W = \begin{bmatrix} 7.1 & & & \\ & 7.1 & & \\ & & 64 & \\ & 0 & & 1 \\ & & & & 1 \end{bmatrix}$$

parameter corrections =

<u>iter</u>	<u>Δx</u>	<u>Δy</u>
1	-0.536	-2.496
2	.0069	-.0007
3	-.0000018	-.0000003
4	.0000000005	.00000000007

final parameters =

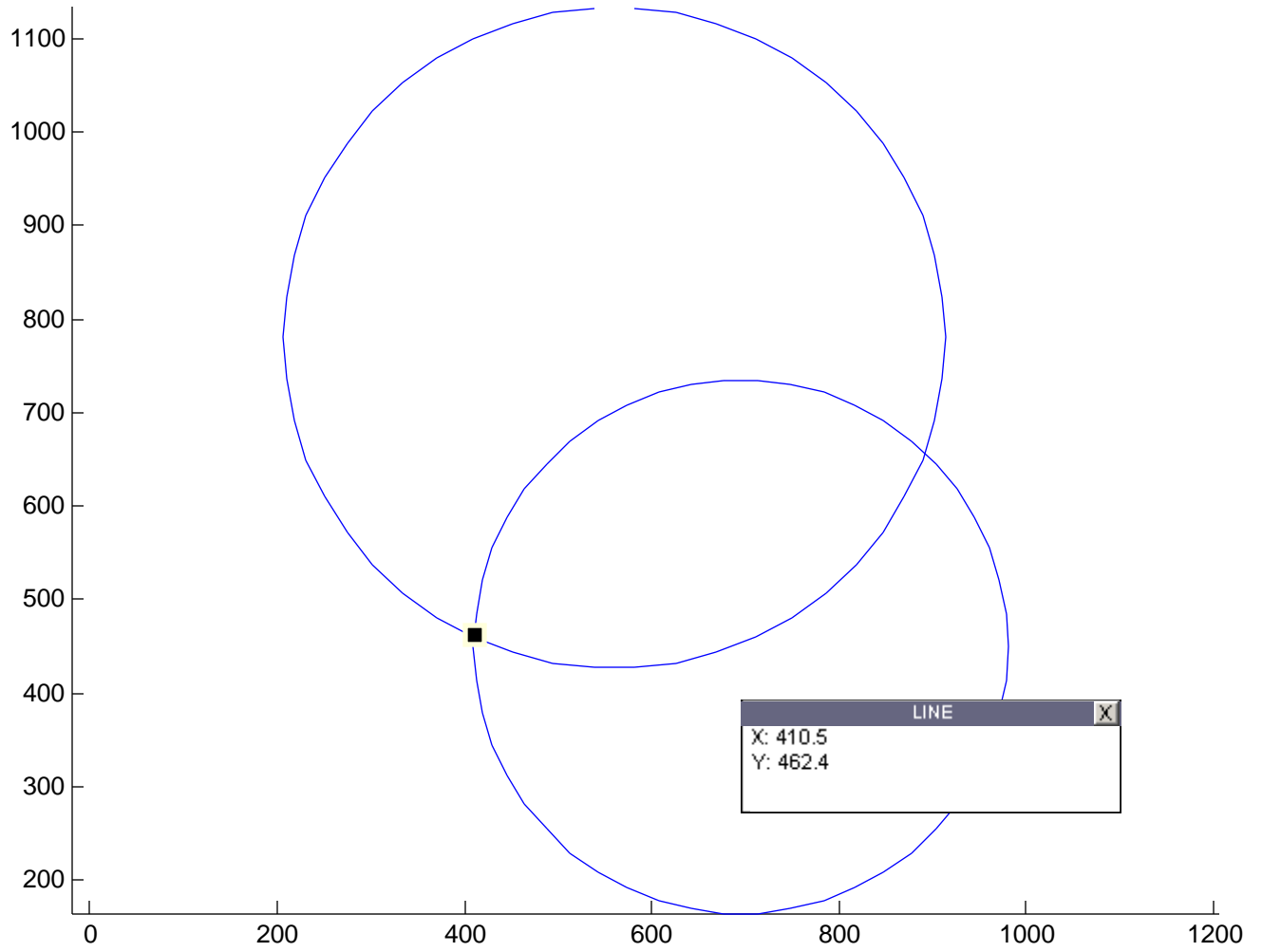
$$\begin{bmatrix} X \\ Y \end{bmatrix} = \begin{bmatrix} 409.97 \\ 459.90 \end{bmatrix}$$

residuals =

$$v = \begin{bmatrix} .062 \\ -.049 \\ 1.008 \\ -.128 \\ .088 \end{bmatrix}$$

adjusted obs =

$$\hat{d} = \begin{bmatrix} 353.51 \\ 285.20 \\ 270.56 \\ 343.05 \\ 298.37 \end{bmatrix}$$



```
% dist5.m 13-oct-08
% initial approx (see graphics for approx)
x0=410.5;
y0=462.4;
n=5;
n0=2;
r=n-n0;
c=n;
u=n0;
B=zeros(c,u);
f=zeros(c,1);
sig0=0.08;
sig=[0.03;0.03;0.01;0.08;0.08];
w=zeros(n,1);
for i=1:n
    w(i)=sig0^2/sig(i)^2;
end
W=diag(w);
X=[560;695;465;85;180];
Y=[780;450;195;350;650];
d=[353.45;285.25;270.55;343.18;298.28];
keep_going=1;
iter=1;
while (keep_going == 1)
    for i=1:n
        D=sqrt((x0-X(i))^2 + (y0-Y(i))^2);
        B(i,1)=-(x0-X(i))/D;
        B(i,2)=-(y0-Y(i))/D;
        Fi=d(i)-D;
        f(i)=-Fi;
    end
    N=B'*W*B;
    t=B'*W*f;
    if(iter==1)
        B
        f
        W
    end;
    iter
    del=inv(B'*W*B)*B'*W*f;
    if (all(abs(del)<1.0e-06) | (iter > 10))
        keep_going=0;
    end
    x0=x0 + del(1);
    y0=y0 + del(2);
    iter=iter+1;
end

[x0 y0]
v=f-B*del
dhat=d + v
```


dist5_1st.txt

dist5

B =

0.42589	0.90477
0.99905	-0.043544
0.19971	-0.97986
-0.94523	-0.3264
-0.77559	0.63124

f =

-2.4229
-0.4799
2.3474
1.1803
-1.0864

w =

7.1111	0	0	0	0
0	7.1111	0	0	0
0	0	64	0	0
0	0	0	1	0
0	0	0	0	1

iter =

1

del =

-0.53606
-2.4965

iter =

2

del =

0.0069202
-0.00071653

iter =

3

del =

-1.8437e-006
-3.7711e-007

iter =

4

del =

5.0073e-010
7.4537e-011

ans =

409.97	459.9
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v =

0.062305
-0.04888
0.0081451
-0.12798
0.088116

dhat =

353.51
285.2
270.56
343.05
298.37

diary off