

I/O $V + B\Delta = f$ } O/O $Av = f$

n B

$\text{rank}(B) = M$

$u = n_0$

n A

$\text{rank}(A) = c$

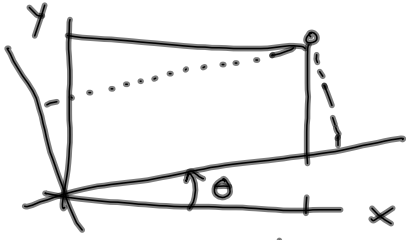
$c = r$

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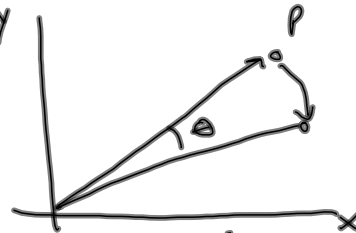
$x' = x \cos \theta + y \sin \theta$
 $y' = -x \sin \theta + y \cos \theta$
 $\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$

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Can interpret rotation in 2 ways



CCW or anticlockwise



CW direction

2D rotation matrix: orthogonal matrix

o determinant = 1

$$\begin{pmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{pmatrix}$$

$$\cos^2\theta + \sin^2\theta = 1$$

o inverse = transpose

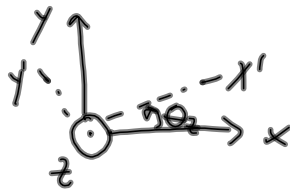
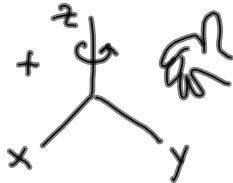
$$\begin{pmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{pmatrix} \begin{pmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

reflection matrix $\det() = -1$



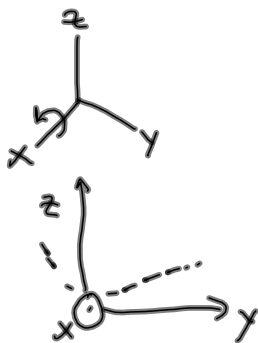
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2D \rightarrow 3D



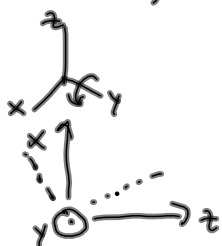
$$\begin{pmatrix} x' \\ y' \\ z' \end{pmatrix} = \begin{pmatrix} \cos\theta_z & \sin\theta_z & 0 \\ -\sin\theta_z & \cos\theta_z & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

M_z, R_z



$$\begin{pmatrix} x' \\ y' \\ z' \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos\theta_x & \sin\theta_x \\ 0 & -\sin\theta_x & \cos\theta_x \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

M_x, R_x



$$\begin{pmatrix} x' \\ y' \\ z' \end{pmatrix} = \begin{pmatrix} \cos\theta_y & 0 & -\sin\theta_y \\ 0 & 1 & 0 \\ \sin\theta_y & 0 & \cos\theta_y \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

M_y, R_y

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$$M = M_z M_y M_x$$

any rotation $R_3 R_2 R_1$

elementary rotation matrices

euler angles $M_x M_y \neq M_y M_x$

$$\begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} \quad \begin{array}{l} 1 \text{ parameter} \\ \text{transf.} \end{array}$$

$$\begin{pmatrix} x' \\ y' \end{pmatrix} = \lambda \cdot \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} \quad \begin{array}{l} 2 \text{ param} \\ \text{transf.} \end{array}$$

$$\begin{array}{l} a = \lambda \cos \theta \\ b = \lambda \sin \theta \end{array} \quad \begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} a & b \\ -b & a \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

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