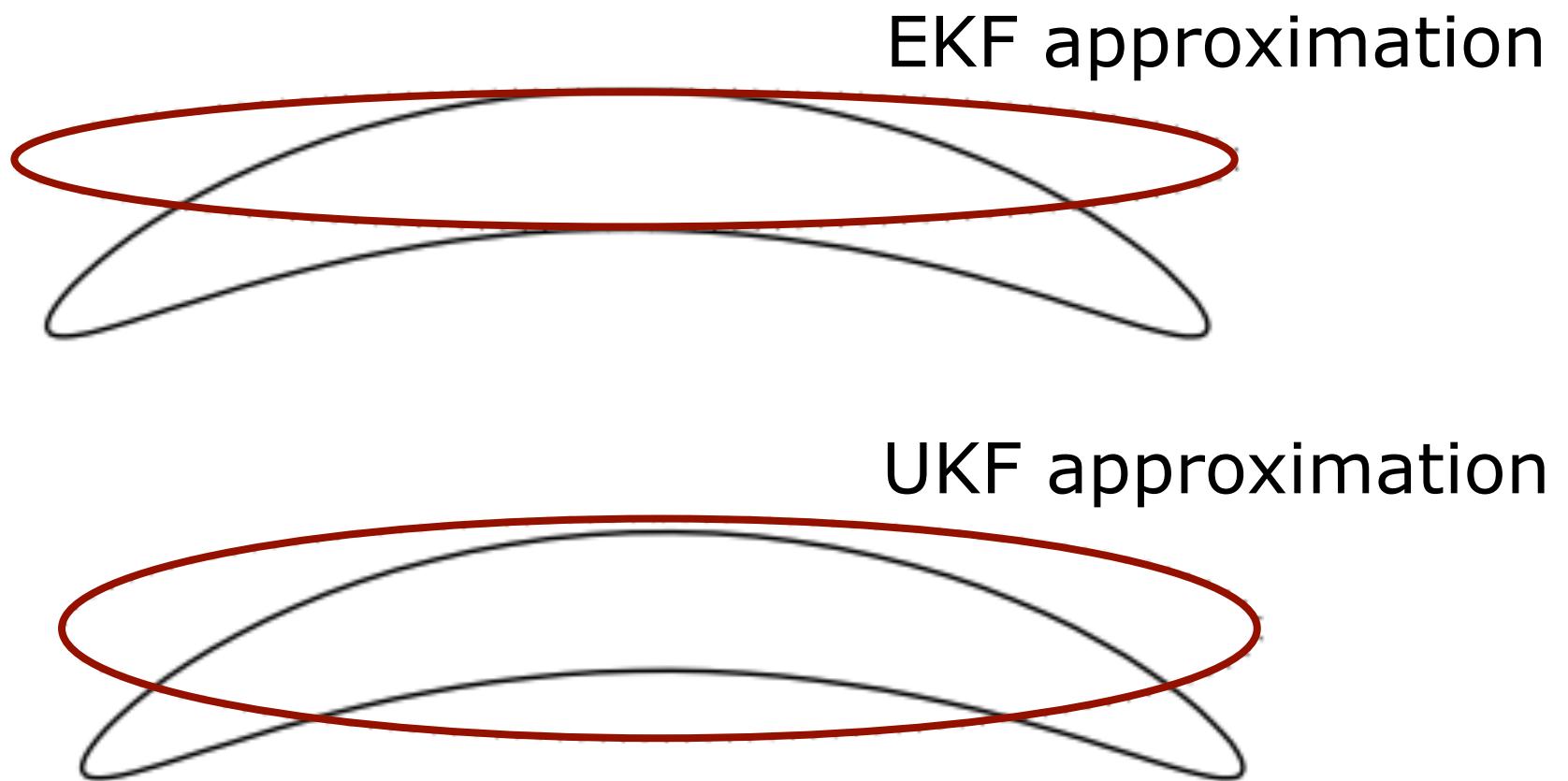
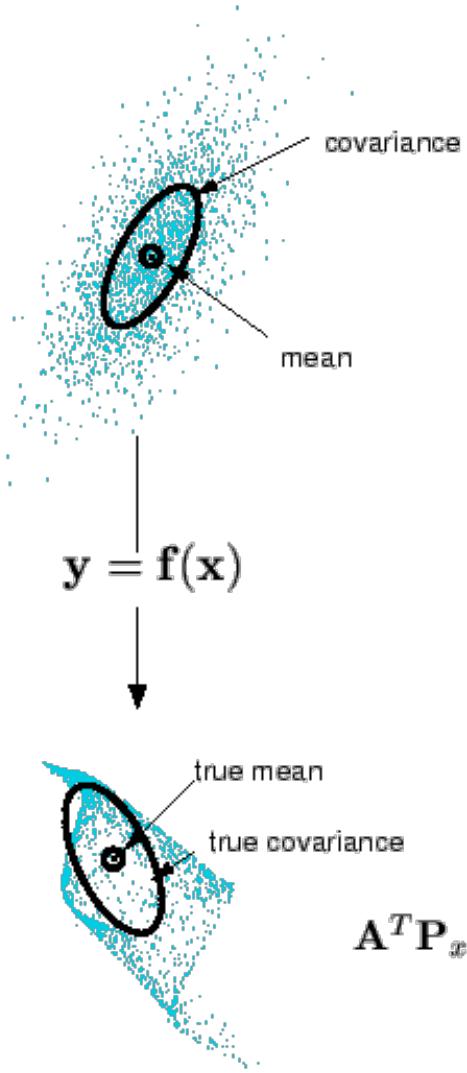


# UKF vs. EKF – Banana Shape

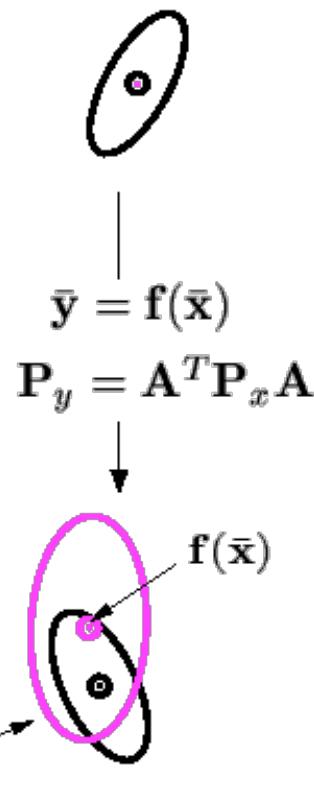


# UKF vs. EKF

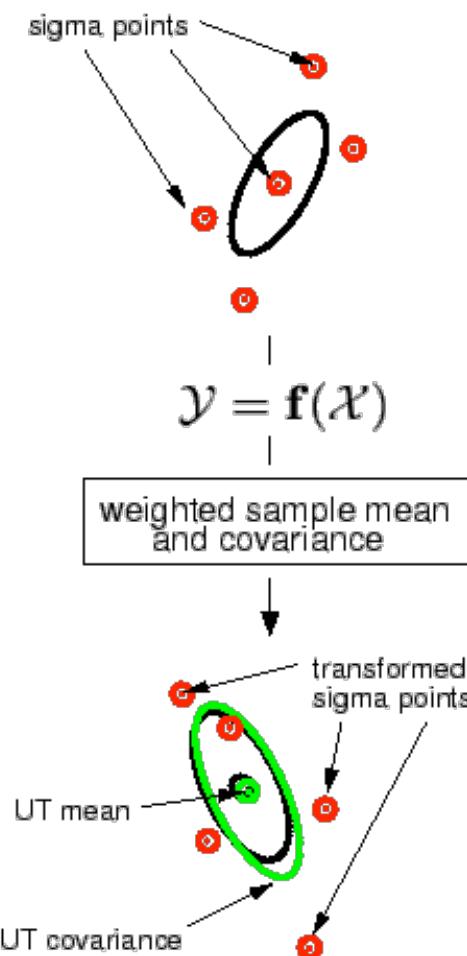
Actual (sampling)



Linearized (EKF)



UT



Courtesy: E.A. Wan and R. van der Merwe

3 examples of Error Propagation  
 (covariance propagation)

$$1. \quad Y = Ax \quad , \quad A = \begin{bmatrix} 0.8 & 0.2 \\ 0.3 & 1.2 \end{bmatrix} , \quad X \sim MVN \left[ \mu_x = \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \Sigma_{xx} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right]$$

lin 01.pdf

$$2. \quad Y = \begin{bmatrix} \sqrt{x_1^2 + x_2^2} \\ \tan^{-1}(x_2/x_1) \end{bmatrix} , \quad J = \begin{bmatrix} \frac{x_1}{\sqrt{x_1^2 + x_2^2}} & \frac{x_2}{\sqrt{x_1^2 + x_2^2}} \\ \frac{-x_2}{x_1^2 + x_2^2} & \frac{x_1}{x_1^2 + x_2^2} \end{bmatrix}$$

$$X \sim MVN \left[ \mu_x = \begin{bmatrix} 0.4 \\ 0.3 \end{bmatrix}, \Sigma_{xx} = \begin{bmatrix} (0.01)^2 & 0 \\ 0 & (0.01)^2 \end{bmatrix} \right]$$

nonlin 01.pdf

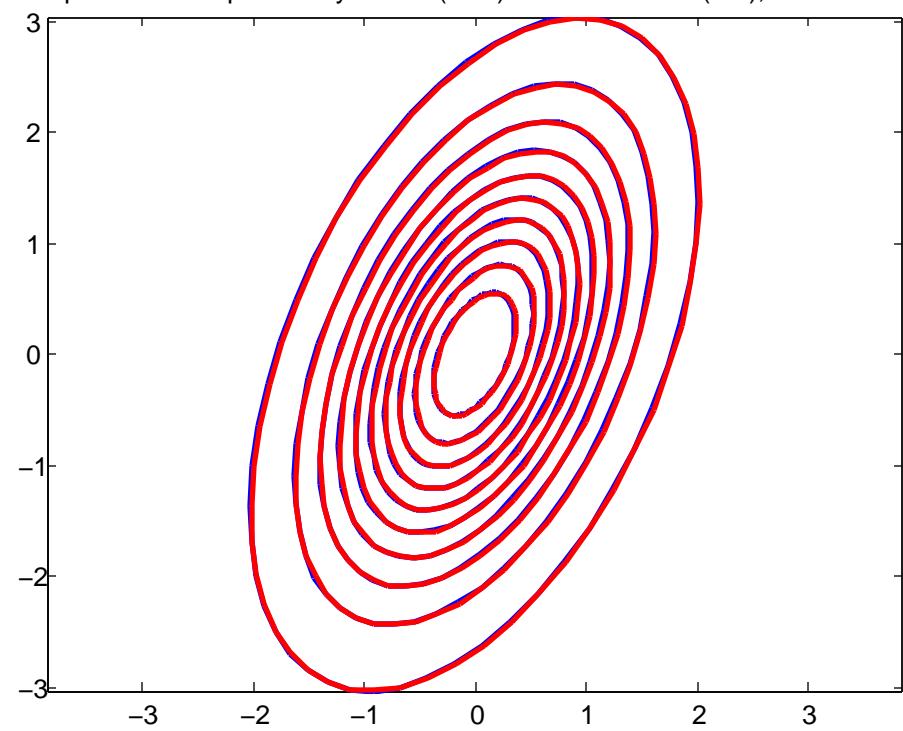
(choose length units = km.)

$$3. \quad Y = \begin{bmatrix} x_1^2 x_2 \\ x_2^3 - x_1^2 \end{bmatrix} , \quad J = \begin{bmatrix} 2x_1 x_2 & x_1^2 \\ -2x_1 & 3x_2^2 \end{bmatrix}$$

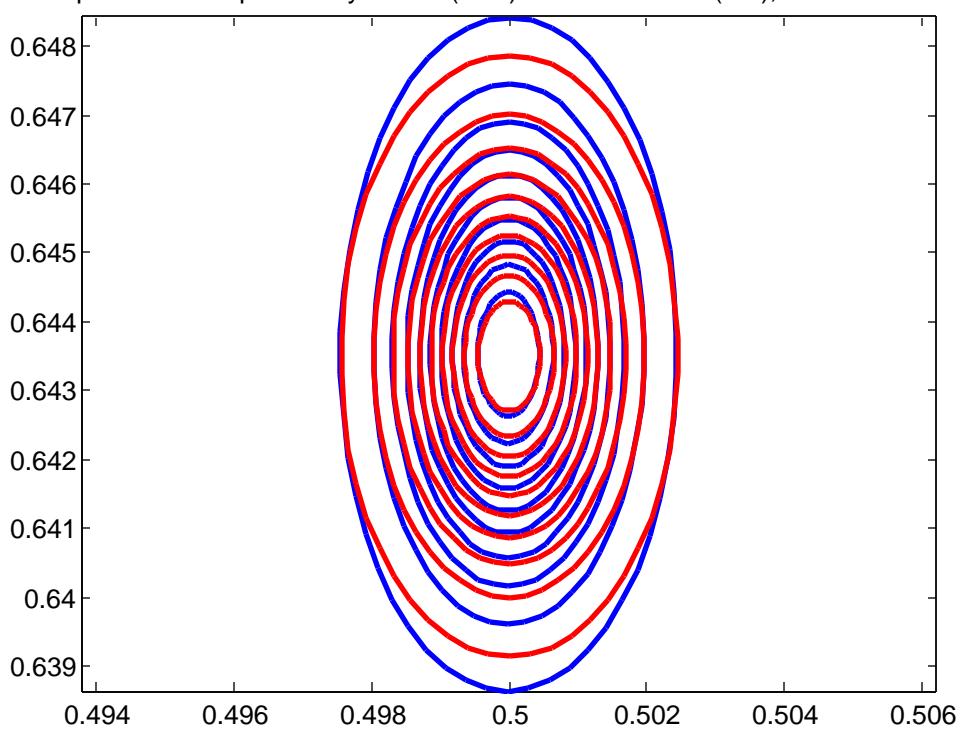
$$X \sim MVN \left[ \mu_x = \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \Sigma_{xx} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right]$$

nonlin 02.pdf

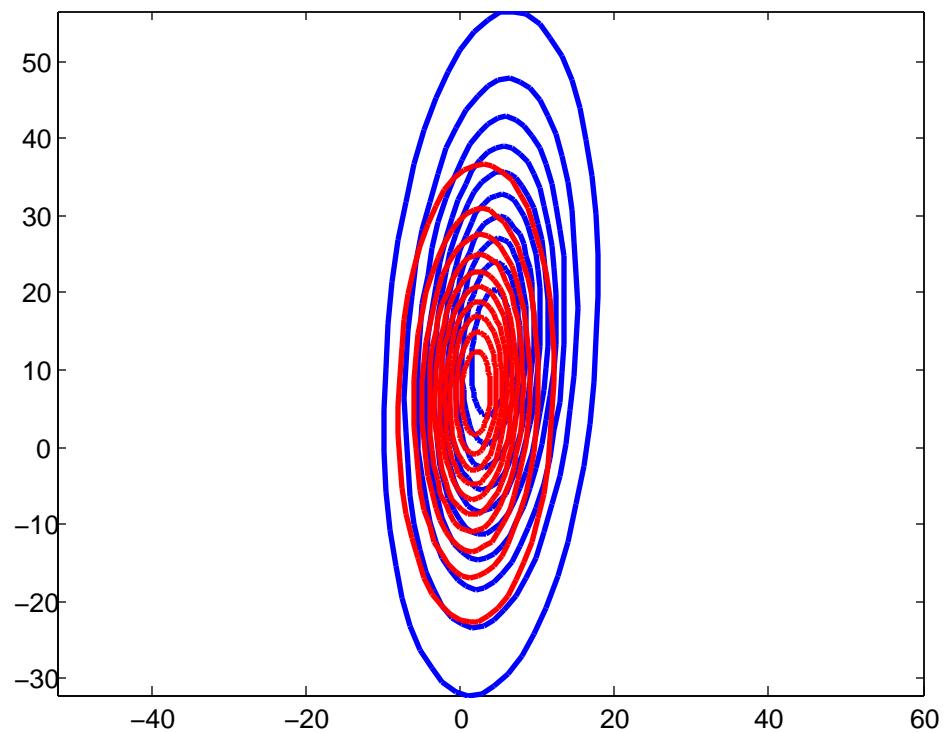
compare bivariate probability for EP (blue) vs. monte carlo (red), linear function



compare bivariate probability for EP (blue) vs. monte carlo (red), nonlinear function



compare bivariate probability for EP (blue) vs. monte carlo (red), nonlinear function



Taken from Phil Kim, K.F. for Beg.

