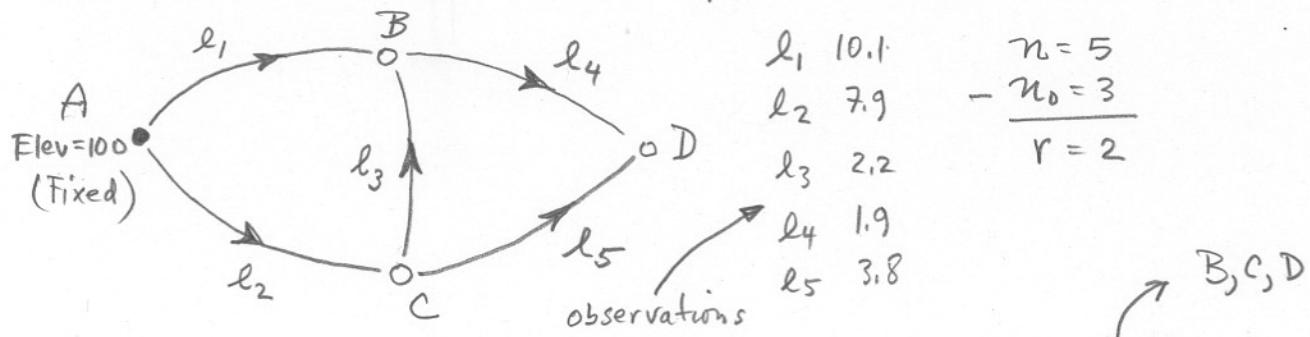


Example: Level Network by Indirect Observations
Model: Absolute elevations of all points in network

CE 506, Fall 2004



With indirect observation method, we carry $n_0 = 3$ unknown parameters, and we write $n = 5$ condition equations, with one observation per equation

$$\begin{array}{lll} 1. \quad l_1 + v_1 = B - 100 & v_1 = B - 100 - 10.1 & v_1 = B - 110.1 \\ 2. \quad l_2 + v_2 = C - 100 & v_2 = C - 100 - 7.9 & v_2 = C - 107.9 \\ 3. \quad l_3 + v_3 = B - C & \Rightarrow v_3 = B - C - 2.2 & \Rightarrow v_3 = B - C - 2.2 \\ 4. \quad l_4 + v_4 = D - B & v_4 = D - B - 1.9 & v_4 = D - B - 1.9 \\ 5. \quad l_5 + v_5 = D - C & v_5 = D - C - 3.8 & v_5 = D - C - 3.8 \end{array}$$



Objective function to Minimize $\Phi = v_1^2 + v_2^2 + v_3^2 + v_4^2 + v_5^2$, differentiate with respect to 3 unknowns B, C, D and set equal to zero.

$$\Phi = (B - 110.1)^2 + (C - 107.9)^2 + (B - C - 2.2)^2 + (D - B - 1.9)^2 + (D - C - 3.8)^2$$

$$\frac{\partial \Phi}{\partial B} = \frac{\partial}{\partial B} (B - 110.1)^2 + \frac{\partial}{\partial B} (B - C - 2.2)^2 + \frac{\partial}{\partial B} (D - B - 1.9)(-1) = 0$$

$$\frac{\partial \Phi}{\partial C} = \frac{\partial}{\partial C} (C - 107.9)^2 + \frac{\partial}{\partial C} (B - C - 2.2)(-1) + \frac{\partial}{\partial C} (D - C - 3.8)(-1) = 0$$

$$\frac{\partial \Phi}{\partial D} = \frac{\partial}{\partial D} (D - B - 1.9) + \frac{\partial}{\partial D} (D - C - 3.8) = 0$$

$$3B - C - D = 110.1 + 2.2 - 1.9$$

$$-B + 3C - D = 107.9 - 2.2 - 3.8 \Rightarrow$$

$$-B - C + 2D = 1.9 + 3.8$$

$$\begin{bmatrix} 3 & -1 & -1 \\ -1 & 3 & -1 \\ -1 & -1 & 2 \end{bmatrix} \begin{bmatrix} B \\ C \\ D \end{bmatrix} = \begin{bmatrix} 110.4 \\ 101.9 \\ 5.7 \end{bmatrix}$$

Solve system with matlab:

$$N = [3 \ -1 \ -1; \ -1 \ 3 \ -1; \ -1 \ -1 \ 2];$$

$$t = [110.4; 101.9; 5.7];$$

$$X = \text{inv}(N) * t;$$

$$B = X(1);$$

$$C = X(2);$$

$$D = X(3);$$

Normal Equations (symmetric)

$$\begin{bmatrix} B \\ C \\ D \end{bmatrix} = \begin{bmatrix} 110.0625 \\ 107.9375 \\ 111.8500 \end{bmatrix}$$

plug into \circledast ↑

adjusted observations

residuals →

$$\begin{bmatrix} V_1 \\ V_2 \\ V_3 \\ V_4 \\ V_5 \end{bmatrix} = \begin{bmatrix} -0.0375 \\ 0.0375 \\ -0.0750 \\ -0.1125 \\ 0.1125 \end{bmatrix}, \begin{bmatrix} \hat{l}_1 \\ \hat{l}_2 \\ \hat{l}_3 \\ \hat{l}_4 \\ \hat{l}_5 \end{bmatrix} = \begin{bmatrix} l_1 + v_1 \\ l_2 + v_2 \\ l_3 + v_3 \\ l_4 + v_4 \\ l_5 + v_5 \end{bmatrix} = \begin{bmatrix} 10.0625 \\ 7.9375 \\ 2.1250 \\ 1.7875 \\ 3.9125 \end{bmatrix}$$