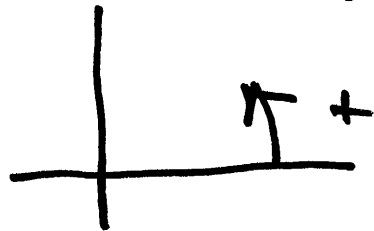


- 1. intersect ray + surface
2. find surface tangent + normal
3. find incidence angle
4. find equation reflected ray

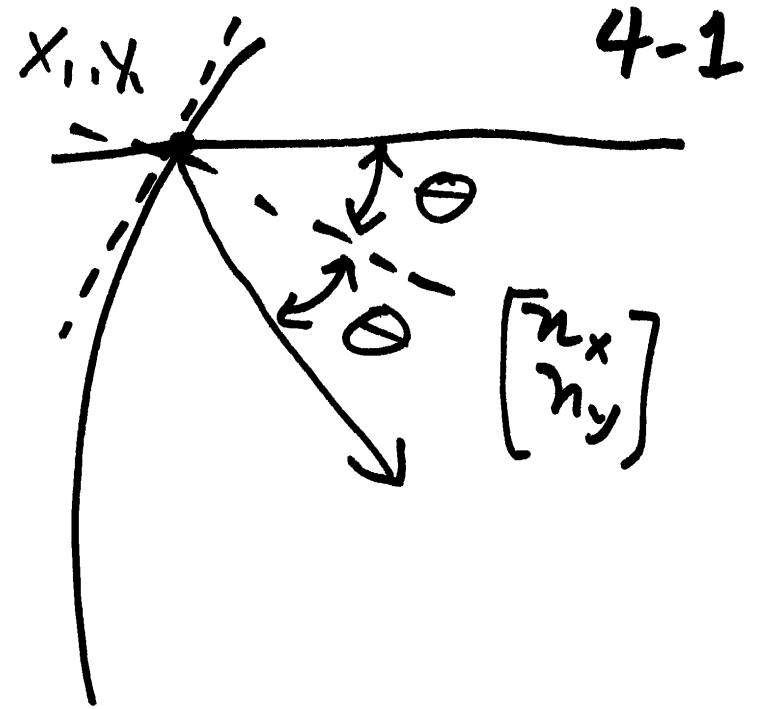
bearing/angle



$$\beta_{\text{ray}} = \tan^{-1} \left(\frac{n_y}{n_x} \right) - \theta$$

↑
(atan2 (m_y, n_x))

$$\text{slope} = m = \tan(\beta)$$



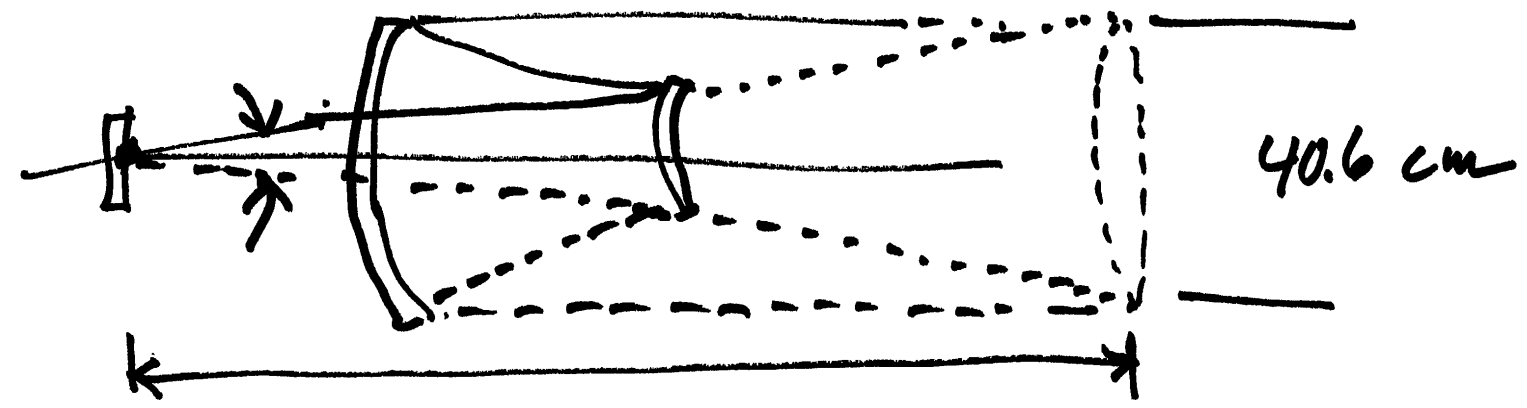
2D

Ray Trace Steps
for homework 1

have $m, x_1, y_1 \Rightarrow y = mx + (y_1 - mx_1)$

4-2

5. do again



~~dot~~ dot product

$$\hat{r} \cdot \hat{n} = r_x n_x + r_y n_y$$

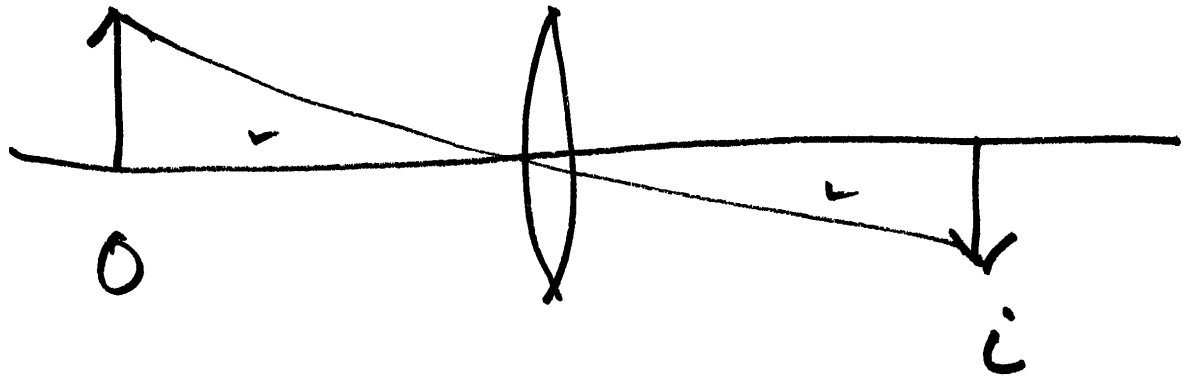
dot(r, n)

magnification

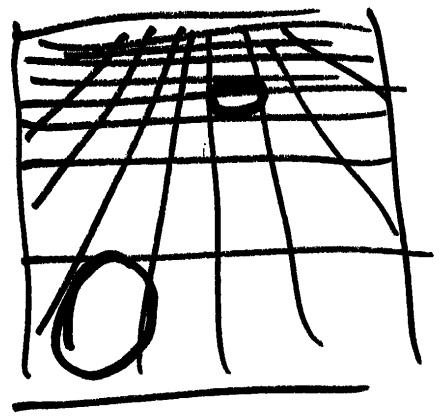
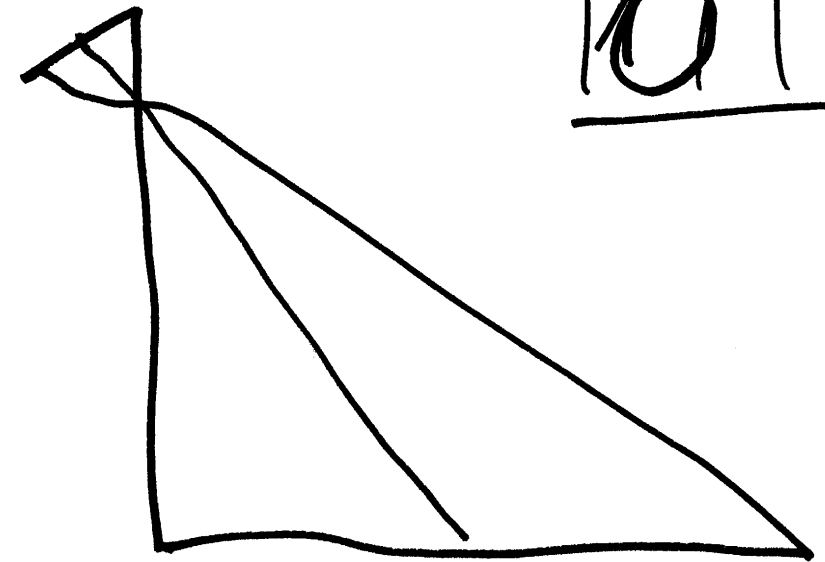
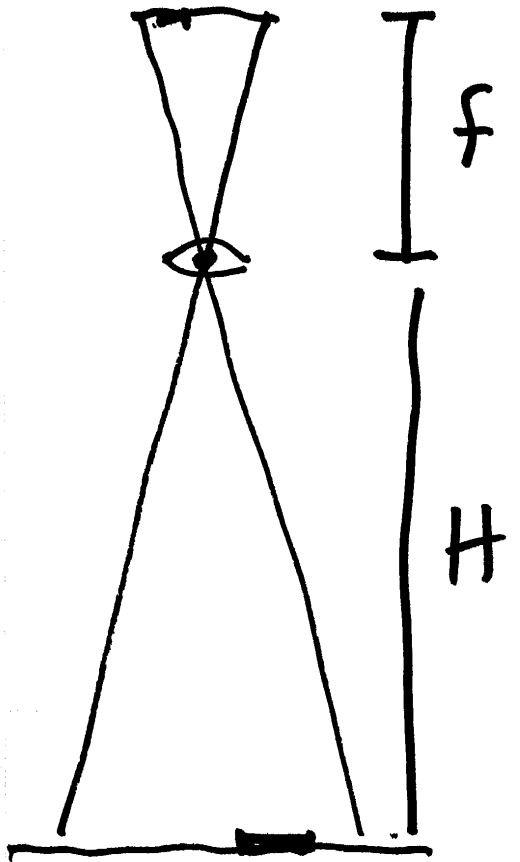
Scale

$$\frac{\text{image size}}{\text{object size}} = \frac{i}{o}$$

meas. \perp to optical axis



$$\text{Scale} = \frac{f}{H}$$



vertical photo ~ constant Scale

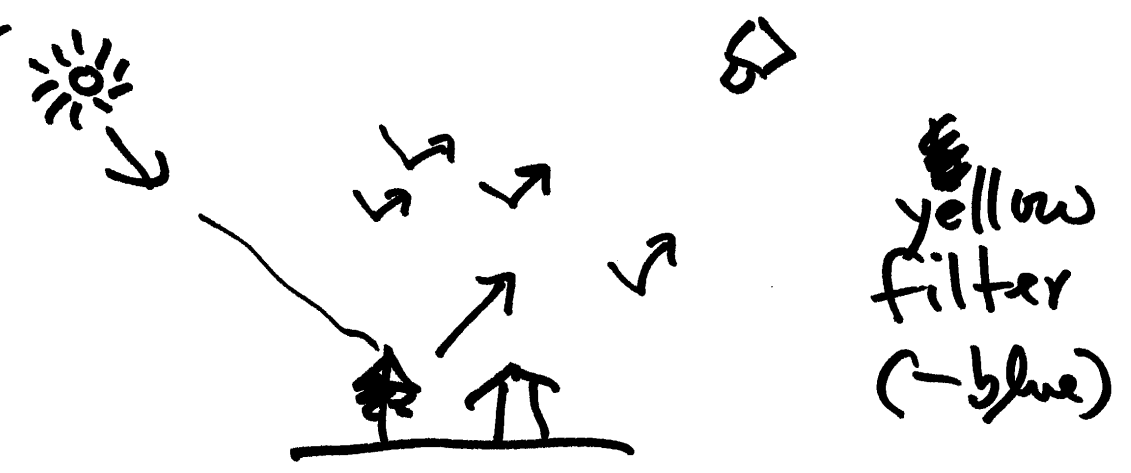
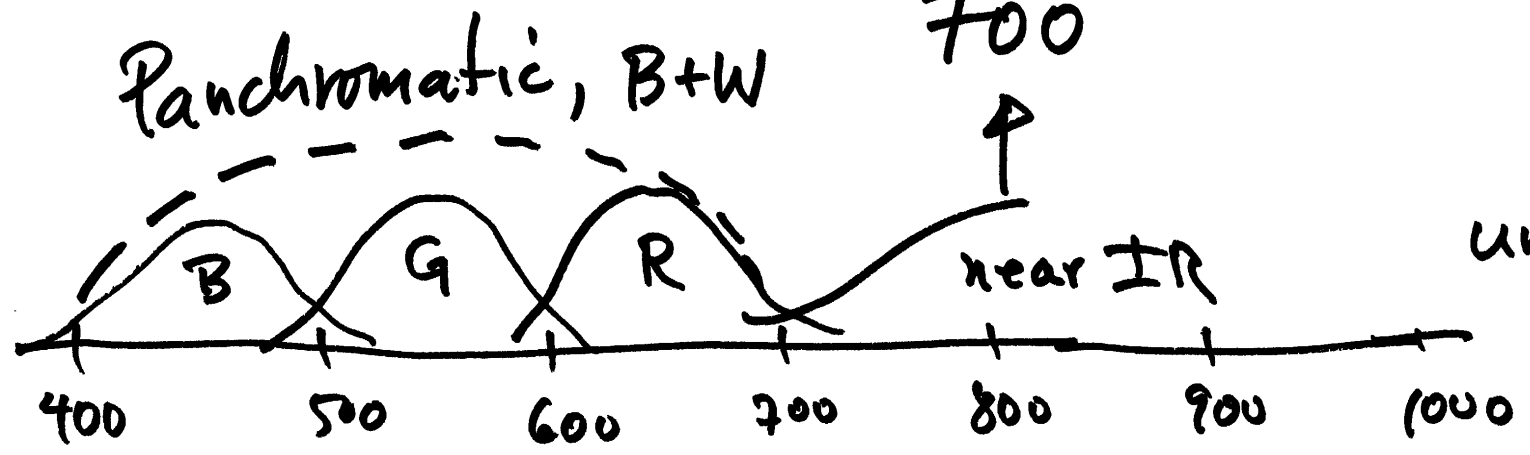
oblique photo ~ scale different everywhere different every direction

example: $f = 152.4 \text{ mm (6")}$
 for
 scale $H = 700 \text{ m}$

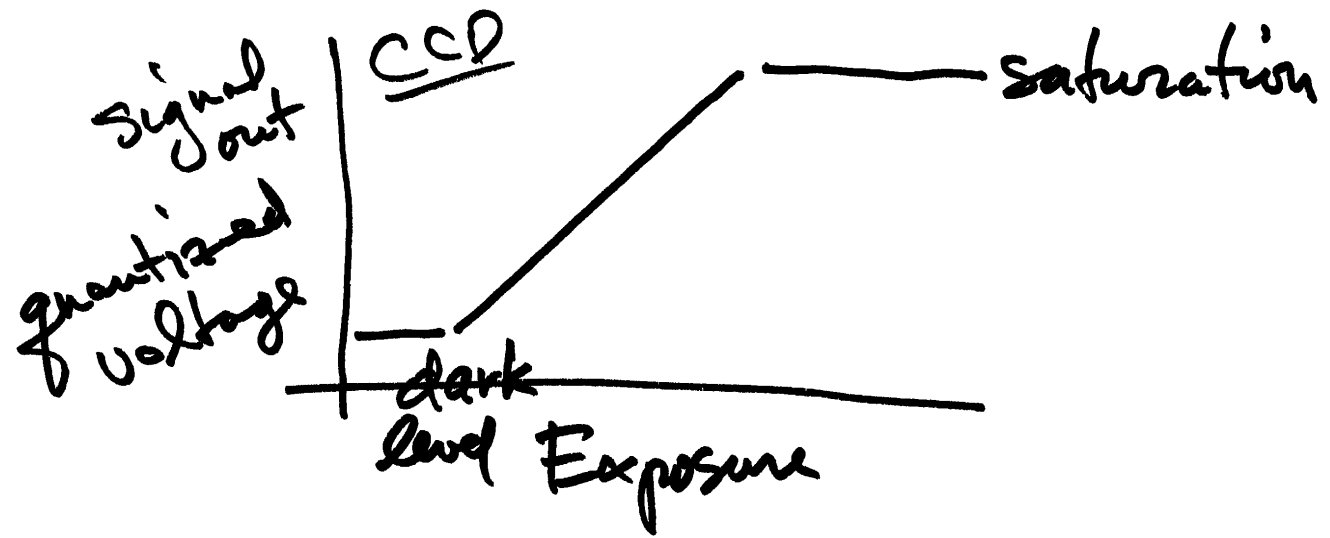
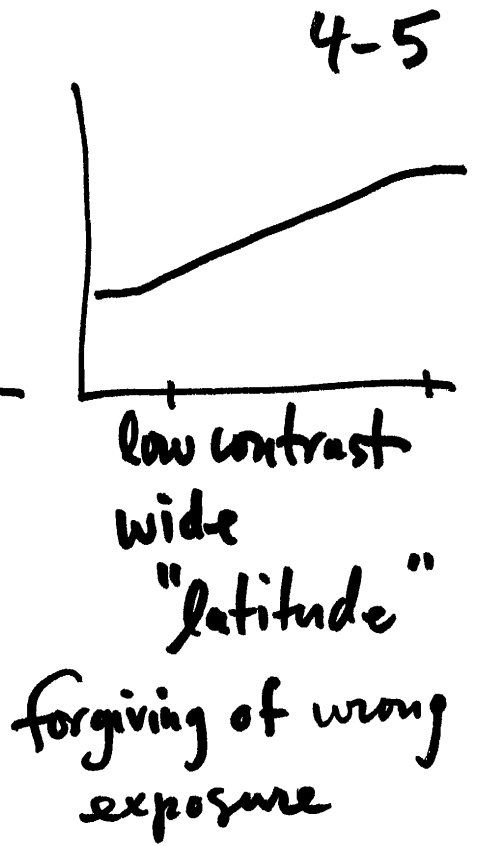
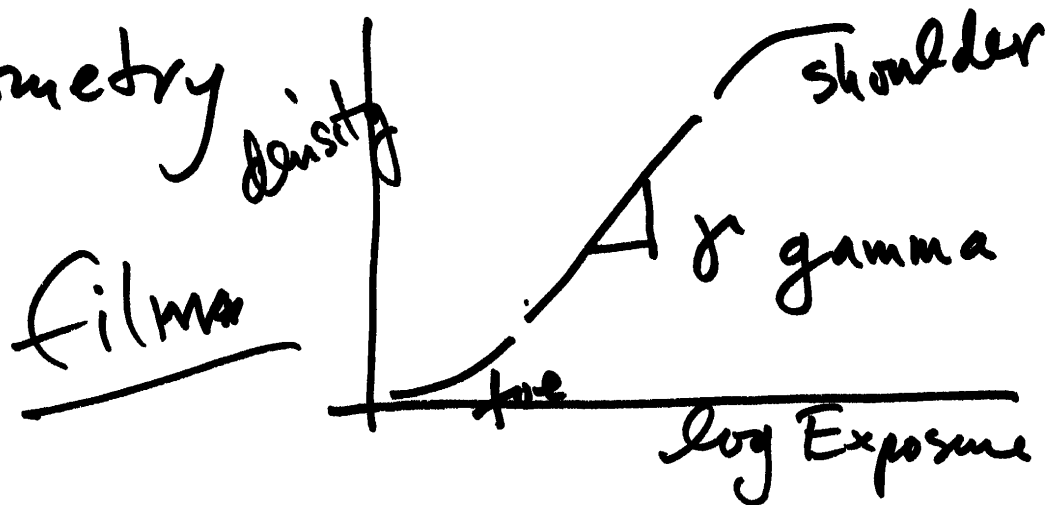
Scale: $\frac{0.1524}{700} = 2.177 \times 10^{-4} = \frac{1}{4593}$

1:4593

unitless ratio



Sensitometry



CCD benefits

more linear response

higher dynamic range

geometrically stable

QE proportion of photons
which produce electron

extra images are "free"

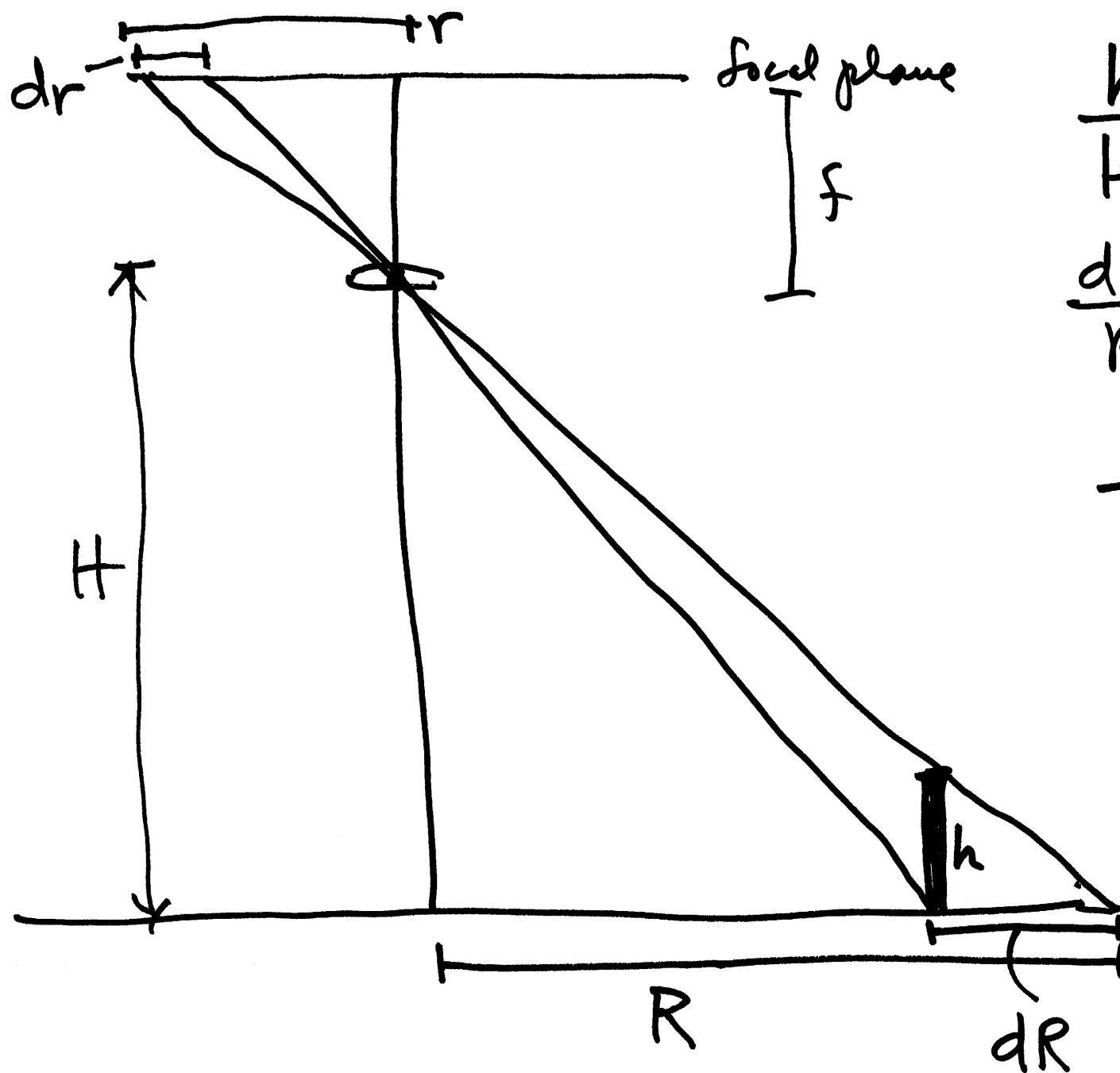
geometry : 46

relief displacement

(frame)

Radar (SAR)

layover



$$\frac{h}{H} = \frac{dR}{R}$$

$$\frac{dR}{R} = \frac{dr}{r}$$

$$\frac{h}{H} = \frac{dr}{r}$$

$$h = \frac{dr}{r} H$$

4-7

height of object
from
single
photograph

Relief Displacement
determine height of object

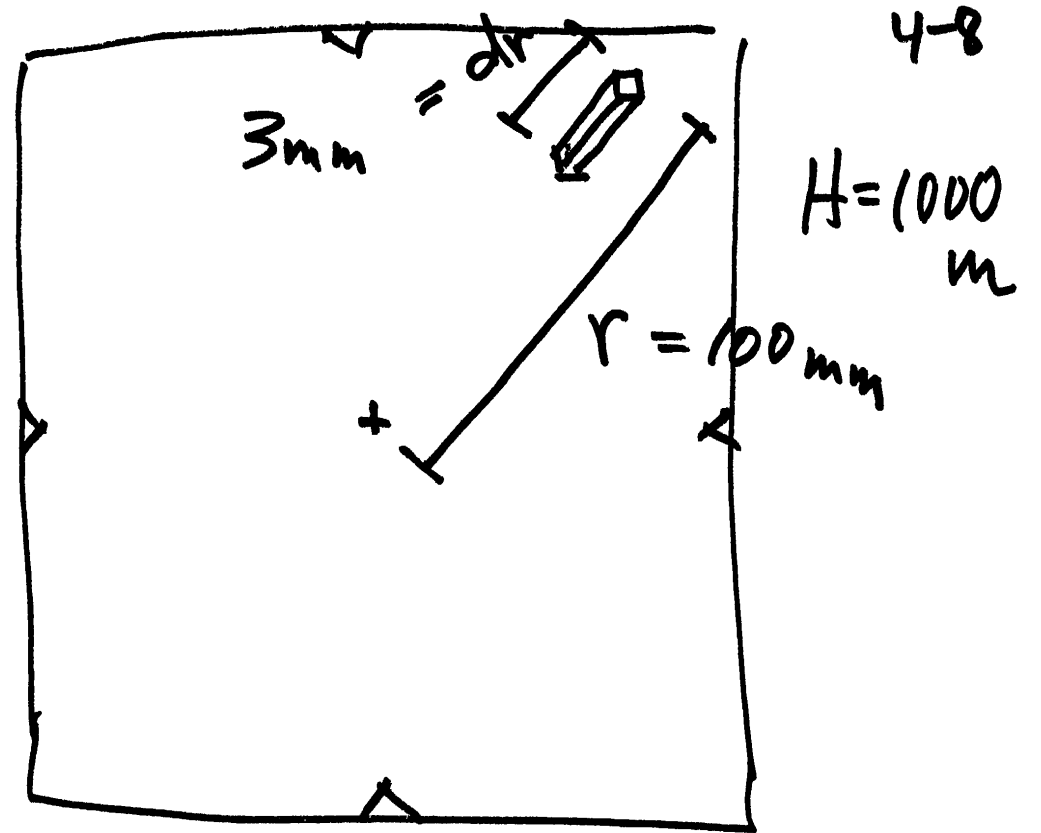
assumed: vertical photo
PP = Nadir point

$$h = \frac{dr}{r} H$$

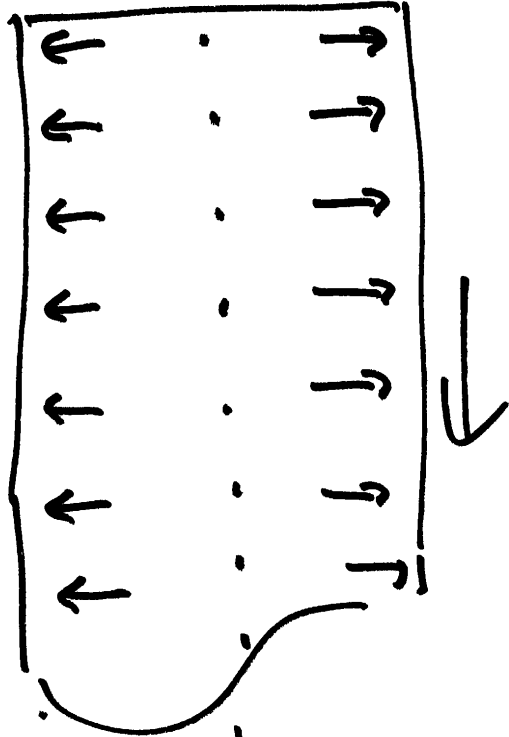
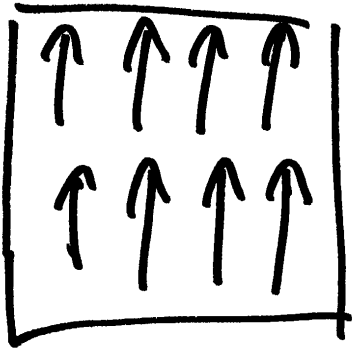
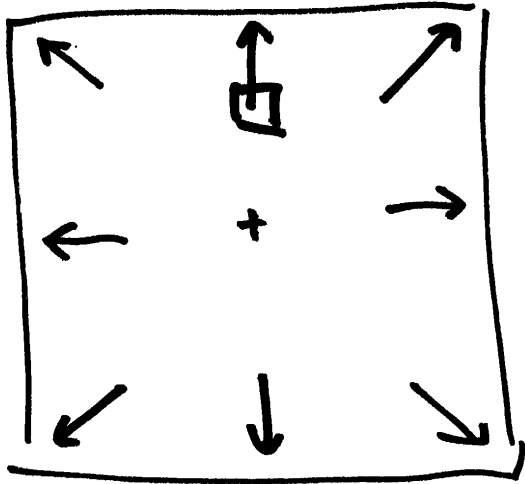
↑
measure

↑
auxiliary sensor
(infer from scale)

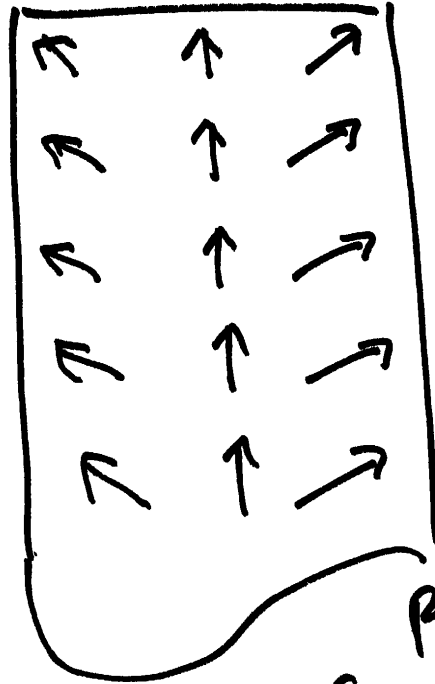
$$h = \frac{3}{100} \cdot 1000 = \underline{\underline{30\text{m}}}$$



example for
relief displacement



pushbroom
nadir
view



pushbroom
forward looking
view

- Relief displacement in
- frame
 - pushbroom

frame (pinhole) ✓
push broom
whistle broom

