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motivation for mirror optics: chromatic aberration, weight on-axis vs. off-axis telescope design history of satellite remote sensing synchronous vs. asynchronous scanning digital globe: worldview 1 reference coordinate systems coordinate transformations

(1) phi,lambda,h -> cartesian, ECF, closed form
(2) ECF -> phi, lambda, h, iterative
(3) ECF -> local cartesian (topocentric) support data: .geo, .ind, .rpb, .eph, .att rotation parameters:
(1) euler angles (roll, pitch, yaw), singularities
(2) direction cosines
(3) quaternions
(4) axis-angle image to ground algorithm systematic errors:
(1) atmosperic refraction
(2) velocity aberration
matlab functions needed:
(1) [X;Xz] '=FIZG[1,s,h], just a wrapper
(3) [dPH; LAM]'=FIZG PL(1,s,h), just a wrapper
(4) [1;s]=FGI(phi,lambda,h), solve eqn (3) for l,s by iteration verify that (2) & (4) are inverses adjustable parameters resection (refine EC given GCP's)
2-image triangulation with tie points and GCP's replacement model standards for replacement model parameters coordinate normalization solving singular NE verify accuracy setup stereo model in LPS image interpolation nearest neighbor bilienear bicubic image pyramid orthorectification integrate with vectors in ArcGIS radiometric units radiometric units radiometric units radiometric units radiometric units radiometric design resolution, resolving power mission design CCD operation

(probably not time for all these topics, maybe some) orbit mechanics, 2-body problem transformation state vector <-> kepler element time concepts solar, sidereal, utl, utc, tai, gps, gast, JD, MJD transformation ECF <-> ECI, precession, nutation, GAST, polar motion velocity transformation
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